

Integral curves contd.: One clarification on using the ODE theorem: if $f: V \rightarrow \mathbb{R}^m$ is continuously differentiable, $V \subseteq \mathbb{R}^d$ open. Then for every $p \in V$, $\exists r > 0$, such that all $\frac{\partial f_i}{\partial x_j}$ are bounded by some $M' > 0$. Then for $M := \sqrt{d}m \cdot M'$, one has, $\forall x, y \in B(0, r)$, $\|f(x) - f(y)\| \leq M \cdot \|x - y\|$. $\square$

We defined the notion of the maximal integral curve for a vector field and the notion of a complete vector field, i.e. that whose all max integral curves have domain $\mathbb{R}$, incomplete q.w. Looking ahead; if X is a complete vector field on M , $\{\gamma_p\}$ its max integral curves, we'll see that $\mathbb{R}$ there is a diffeomorphic action of $\mathbb{R}$ on M , i.e. a group homom. $\Phi_X: \mathbb{R} \rightarrow \text{Diff}(M)$, induced from $\mathbb{R} \times M \rightarrow M$ given by $(t, p) \mapsto \gamma_p(t)$. In particular if we write $\varphi_t(p) := \gamma_p(t)$, then

$$\varphi_s \circ \varphi_t = \varphi_{s+t}$$



¹⁴⁻² This is the analogue of translations on M , and we'll use this to compare tangent spaces at different points on M . $\square$

Local flows :- Let M be smooth and X a smooth vector field on M , $p \in M$. Then $\exists \epsilon > 0$, open $U \subseteq M$, $p \in U$ and a unique smooth map $F: (-\epsilon, \epsilon) \times U \rightarrow M$ with $F(0, x) = x \forall x \in U$, $\frac{d}{dt}(F(x, t)) = X(F(x, t)) \forall t \in (-\epsilon, \epsilon), x \in U$.

In other words $\exists$ a unique family of integral curves of X on U , having the same domain $(-\epsilon, \epsilon)$, passing through pts of U . $\square$

$I \neq$ With the above notation, denote for $(t, z) \in (-\epsilon, \epsilon) \times U$, $\varphi_t(z) := F(t, z)$. If γ_p be as before, $\gamma_p(t) = F(t, p)$ for $t \in I$.

$\rightarrow$ When X is complete, $\varphi_t: M \rightarrow M$ is a diffeomorphism, since $\varphi_s \circ \varphi_t(p) = \varphi_{s+t}(p)$, $\varphi_0(p) = p \forall p \in M$.

Proof :- For a fixed s , we consider the curves $t \mapsto \varphi_s \circ \varphi_t(p)$ and $t \mapsto \varphi_{s+t}(p)$.

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Then both have initial condition $= \varphi_s(p)$ and are integral curves of X . Hence they must be equal (having domains $= \mathbb{R}$). Inverse of φ_t is φ_{-t} clearly. $\square$

Defⁿ: $\{\varphi_t\}_{t \in \mathbb{R}}$ is called the one parameter group of diffeomorphisms associated to X .

Even when X is not complete one can define a local notion:

Defⁿ: A local 1-parameter family of local diffeomorphisms is a collection $\{U_\alpha, \varphi_t^\alpha, \epsilon_\alpha\}_\alpha$ satisfying: (i) U_α are open, $\bigcup_\alpha U_\alpha = M$ (ii) $\epsilon_\alpha > 0 \forall \alpha$ (iii) domain of $\varphi_t^\alpha \supseteq U_\alpha$ and the map $(t, z) \mapsto \varphi_t^\alpha(z)$ for $z \in U_\alpha$ & $t \in (-\epsilon_\alpha, \epsilon_\alpha)$, is smooth.

(iv) $\varphi_t^\alpha(z) = \varphi_t^\beta(z) \forall z$ in $\text{domain}(\varphi_t^\alpha) \cap \text{dom}(\varphi_t^\beta)$ & t with $|t| < \min\{\epsilon_\alpha, \epsilon_\beta\}$.

(v) for t, s with $t, s, t+s \in (-\epsilon_\alpha, \epsilon_\alpha)$, $\varphi_t^\alpha \circ \varphi_s^\alpha$ is defined on an open set $\supseteq U_\alpha$ & $\varphi_t^\alpha \circ \varphi_s^\alpha = \varphi_{t+s}^\alpha$ on U_α . $\rightarrow$

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• Examples / Exercise : 1. Let $M = \mathbb{R}$. Then $\varphi_t: \mathbb{R} \rightarrow \mathbb{R}$

given by (i) $\varphi_t(x) = x + t$ (ii) $\varphi_t(x) = e^t x$ are both one-parameter groups of diffeoms.

2. $M = \mathbb{R}^2$, $\varphi_t(x, y) = (\cos t x - \sin t y, \sin t x + \cos t y)$ is a one-param. group of diffeoms on $\mathbb{R}^2$.

3. $M = \mathbb{R}^n$ and $A \in M_n(\mathbb{R})$ be fixed. Then

$t \mapsto \exp(tA) =: \varphi_t$; $x \mapsto \varphi_t(x)$ is a one-param family of diffeoms.

• Lemma : Given a local 1-parameter family $\{\varphi_t^\alpha\}$ of M , $\exists$ a vector field $X \in \mathcal{X}(M)$ such that it generates the family.

Pf:- We define, for $p \in M$ & $X \in \mathcal{X}(M)$,
 $X(p)(f) := \left. \frac{d}{dt} f \circ \varphi_t^\alpha \right|_{t=0}$ Then X indeed is

smooth. (?) . Let $p \in U_\alpha$ and define

$\gamma_p: (-\epsilon_\alpha, \epsilon_\alpha) \rightarrow M$ by $\gamma_p(t) = \varphi_t^\alpha(p)$. Then

γ_p is an integral curve to X , $\gamma_p(0) = p$

etc.

→ For a given X , a local family of diffeoms is not unique nec. ⊠

14-5 Example/exercise:- Let $X \in \mathcal{X}(M)$,

$\psi: M \rightarrow M$ a diffeomorphism. Let Y be the "push forward" vector field, i.e. for $q \in M$,

$q = \psi(p)$, $Y(q) = D\psi(p)(X(p))$. Then $Y \in \mathcal{X}(M)$. If $\{(U_\alpha, \varphi_t^\alpha, \epsilon_\alpha)\}$ is a local

one parameter family of diffeos for X , then $\{(\psi(U_\alpha), \psi \circ \varphi_t^\alpha \circ \psi^{-1}, \epsilon_\alpha)\}_\alpha$ is one for Y .

Complete vector fields: We have some situations which yield complete fields.

- Let $X \in \mathcal{X}(M)$. ~~Let~~ Assume that X admits a local one-param. family $\{(U_\alpha, \varphi_t^\alpha, \epsilon_\alpha)\}_\alpha$ of local diffeos with $\inf \epsilon_\alpha > 0$. Then X is complete.

Proof (sketch): Let $\epsilon = \inf \epsilon_\alpha > 0$ and define $\varphi_t(p) := \varphi_t^\alpha(p)$, if $p \in U_\alpha$, $t \in (-\epsilon, \epsilon)$. Extend φ_t to the whole of $\mathbb{R}$ by the recipe:

$$\varphi_t := \underbrace{\varphi_{t/n} \circ \dots \circ \varphi_{t/n}}_{n\text{-fold}}, \quad n \text{ is s.t. } t/n \in (-\epsilon, \epsilon).$$

$\leadsto$

14-6. Then φ_t is well defined and $\gamma_p(t) := \varphi_t(p)$ is a max integral curve for X with $\gamma_p(0) = p$ and domain $= \mathbb{R}$. Hence X is complete. $\square$

Vector fields on M compact / Lie groups:

Let M be compact & $X \in \mathcal{X}(M)$.

Lemma: X is complete.

PF: Let $\{(U_\alpha, \varphi_t^\alpha, \epsilon_\alpha)\}$ be a local one-param. family for X . Compactness $\Rightarrow$ finitely many U_α 's cover X , say $U_{\alpha_1}, \dots, U_{\alpha_r}$.

Then $\{(U_{\alpha_i}, \varphi_t^{\alpha_i}, \epsilon_{\alpha_i})\}$ is a 1-param family for X with $\inf \epsilon_{\alpha_i} > 0$. Hence X is complete. $\square$

$\rightarrow$ If M be smooth & $X \in \mathcal{X}(M)$ have compact support, then X is complete.

This follows by working with an open subset containing the support of X , instead of M .



Lemma :- Let G be a Lie group and $X \in \mathfrak{g}$ i.e. X is a left-inv. vector field on G . Then X is complete.

Proof :- Let $\{(U_\alpha, \varphi_t^\alpha, \epsilon_\alpha)\}_\alpha$ be a 1-param. family for X as above. Let $e \in G$ be the identity element of G , $e \in U_{\alpha_0}$. Then the family $\{(L_g(U_{\alpha_0}), L_g \circ \varphi_t^{\alpha_0} \circ L_{g^{-1}}, \epsilon_{\alpha_0}), g \in G\}$ is a local 1-param. family for $DL_g(X) = X$, as X is left-inv. The criterion for completeness is thus satisfied by this family; hence X is complete. $\square$

Exponential map :- Let M be smooth and X a complete smooth vector field on M . Let $\{\varphi_t\}_{t \in \mathbb{R}}$ be the 1-param group of diffeoms associated to X . We define the exponential map of X by $\text{Exp}_x(p) := \varphi_1(p) = \gamma_p(1)$,
so $\text{Exp}_x : M \rightarrow M$. $\leadsto$

Examples :- 1. Let $A = (a_{ij}) \in M_n(\mathbb{R})$. Consider the vector field $\hat{A}$ on $\mathbb{R}^n$ defined by

$$\hat{A} = \sum_{i,j} a_{ij} x_j \frac{\partial}{\partial x_i}$$

Consider $F: \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ given by

$$F(t, x) = e^{tA}(x), \text{ where recall}$$

$$e^{tA} = \sum_j \frac{t^j}{j!} A^j. \text{ Clearly } F \text{ is smooth.}$$

This defines a flow for $\hat{A}$. Setting

$$\varphi_t(x) = e^{tA} x \quad (x \text{ a column vector}),$$

$$\text{we have } \varphi_{t_1+t_2} = \varphi_{t_1} \circ \varphi_{t_2}, \quad \varphi_0 = 1.$$

$$\text{Let } \gamma_p(t) = F(t, p) = e^{tA} p. \text{ Then for } f \in C^\infty(\mathbb{R}^n),$$

$$\begin{aligned} \dot{\gamma}_p(0)(f) &= \left. \frac{d}{dt} f(e^{tA} p) \right|_{t=0} = \sum_j \frac{\partial f}{\partial x_j} (Ap)_j \\ &= \sum_{j,k} a_{jk} p_k \frac{\partial f}{\partial x_j}, \text{ where} \end{aligned}$$

$$p = \begin{pmatrix} p_1 \\ \vdots \\ p_n \end{pmatrix}. \text{ Hence } \dot{\gamma}_p(0) = \hat{A}(p).$$

$$\text{Thus } \text{Exp}_{\hat{A}}(p) = \varphi_1(p) = \gamma_p(1) = e^A \cdot p$$



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 2. Lie groups: G be a Lie group, $\mathfrak{g} = \text{Lie}(G)$.
 We saw that any $X \in \mathfrak{g}$ is complete, so Exp_X makes sense. We define (note the confusing notation!)

$$\exp(x) := \bar{\text{Exp}}_x(e) = \varphi_1(e),$$

and more generally,

$$\exp(tx) = \varphi_t(e), \text{ where } \{\varphi_t\}$$

is the 1-parameter group assoc. to X .

This defines a map $\mathfrak{g} \xrightarrow{\exp} G$

$$x \mapsto \exp(x),$$

called the exponential map of G .

For $G = \text{GL}_n(\mathbb{R})$, we have seen that $\mathfrak{g} = (M_n(\mathbb{R}), [\cdot, \cdot])$, where $A \in M_n(\mathbb{R})$ corresponds to the vector field $\tilde{A} = \sum_{i,j} a_{ij} \frac{\partial}{\partial a_{ij}}$.

We then have the 1-parameter group $\{\varphi_t\}$ associated to $\tilde{A}$, and $\text{Exp}_{\tilde{A}}(e) = \varphi_1(e)$

$\exp(\tilde{A})$ is the exponential of $\tilde{A}$. While

$$\exp(t\tilde{A}) = \varphi_t(e).$$

Consider the curves $\gamma: t \mapsto e^{tA}$ on $\text{GL}_n(\mathbb{R})$.

By defⁿ of the maps $t \mapsto \exp(t\tilde{A})$,
 we have $\exp(t\tilde{A})$ is the maximal int.
 curve of $\tilde{A}$ through I , while γ satisfies

$$\begin{aligned} \dot{\gamma}(0)(f) &= \frac{d}{dt} \Big|_{t=0} (f \circ \gamma) \quad (f \in C^\infty(\text{GL}_n)) \\ &= \frac{d}{dt} \Big|_0 f(e^{tA}) = \sum \frac{\partial f}{\partial x_{ij}} (A)_{ij} \\ &= \left(\sum a_{ij} \frac{\partial}{\partial x_{ij}} \Big|_I \right) (f). \\ &= \tilde{A}(I)(f). \end{aligned}$$

Hence γ is the max int. curve of
 $\tilde{A}$ through I . Thus $\exp(tA) = e^{tA}$
 $\forall A \in M_n(\mathbb{R})$. $\square$

By a similar computation (use left-inv.)
 to prove

Lemma:- For a Lie group G , $g \in G$ and
 $X \in \mathfrak{g}$, we have $\text{Exp}_X(g) = L_g(\exp(X))$

Corollary:- For $X \in \mathfrak{g}$, the flow of X
 is given by $F_X(t, g) = g \exp(tX)$.

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