

Lecture - 15

Some recalls $\Rightarrow$ We are studying vector fields on a smooth manifold M . We define a smooth vector field as a map $X: M \rightarrow T(M) = \bigcup_p T_p M$ such that $X(p) \in T_p M \forall p \in M$ and on any local chart (U, φ) of M , $X(q) = \sum f_i(q) \frac{\partial}{\partial x_i}|_q$, $q \in U$; all f_i are smooth wrt any chart.

$\rightarrow$ The set of all smooth vector fields on M is a real vector space $\mathcal{X}(M)$.

$\rightarrow$ For $X, Y \in \mathcal{X}(M)$, (thinking of X as a derivation: $C^\infty(M) \rightarrow C^\infty(M)$; $X(f)(p) := X(p)(f)$)

$[X, Y] := X \circ Y - Y \circ X \in \text{Der}_{\mathbb{R}}(C^\infty(M), C^\infty(M))$ is a vector field, $(\mathcal{X}(M), [\cdot, \cdot])$ is a Lie algebra.

Rem: In general $X \circ Y$ is not a vector field as this may involve higher order diff. operators

• For $X \in \mathcal{X}(M)$, $f \in C^\infty(M)$, $\mathcal{L}_X: C^\infty(M) \rightarrow C^\infty(M)$
 $\equiv \mathcal{L}_X(f)(p) := X(p)(f)$; $\mathcal{L}_X(f)$ is called the Lie derivative of f w.r.t X .

We can think of $\mathcal{L}_X(f)$ as the function giving, for $p \in M$, the 'directional derivative' of f

¹⁵⁻² at p , in the direction of $X(p) \in T_p M$.

→ $\mathcal{X}(M)$ is a $C^\infty(M)$ -module. For $f \in C^\infty(M)$, $X \in \mathcal{X}(M)$, $(fX)(p) := X(p)(f)$ defines the module structure.

→ $[\cdot, \cdot]: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$ is only $\mathbb{R}$ -bilinear, not $C^\infty(M)$ -bilinear.*

→ $\mathcal{L}_X(Y) := [X, Y]$ is the Lie derivative of Y w.r.t X .

$$\begin{aligned} * [fX, gY] &= fg[X, Y] + f(Xg)Y - g(Yf)X, \\ f, g &\in C^\infty(M). \end{aligned}$$

→ M, N smooth, $\varphi: M \rightarrow N$ smooth; $X \in \mathcal{X}(M)$, $Y \in \mathcal{X}(N)$ are φ -related if $\forall p \in M$, $D\varphi(p)(X(p)) = Y(\varphi(p))$.

• X, Y are φ -related $\Leftrightarrow X(g \circ \varphi) = Y(g) \circ \varphi$
 $\forall g \in C^\infty(N)$.

$$\begin{aligned} M &\xrightarrow{\varphi} N, \quad D\varphi(p): T_p M \rightarrow T_{\varphi(p)} N \\ D\varphi(p)(X(p))(g) &= X(p)(g \circ \varphi) \\ &\equiv Y(\varphi(p)) \quad \forall p. \end{aligned}$$

Lie groups: • Here the important notion is of left inv. vector fields. If G be a Lie grp $X \in \mathcal{X}(G)$ is left-inv. if $D L_g \circ X = X \circ L_g$ $\forall g \in G$.

• Hence left-inv. vect. fields on G are completely determined by their value at $e \in G$.

¹⁵⁻³
 $\rightarrow$ If X, Y are left inv. vector fields on G , then $[X, Y]$ is left-inv. Hence the subspace $\mathfrak{g}$ of $\mathcal{X}(G)$ is a Lie sub-algebra. The map

$$T_e G \rightarrow \mathfrak{g}, \quad v \mapsto X_v: X_v(g) \in T_g G$$

is given by $X_v(g) := DL_g(e)(v) \in T_g G$.

$\rightarrow$ We identify $\mathfrak{g}$ with $T_e G$ via this isomorphism of $\mathbb{R}$ -vector spaces and give $T_e G$ a Lie alg. structure via this, i.e.

$$[v, w] := [X_v, X_w].$$

• Integral curves, flows of vect. fields:-

Given $X \in \mathcal{X}(M)$ & $p \in M$, $\exists \epsilon > 0$ and a curve $\gamma: (-\epsilon, \epsilon) \rightarrow M$ s.t. $\gamma(0) = p$, $\dot{\gamma}(0) \in T_p M$ and $X(p) = \dot{\gamma}(0)$. We call such a curve an integral curve of X through p , if $\forall t \in (-\epsilon, \epsilon)$, we have, in addition, $X(\gamma(t)) = \dot{\gamma}(t)$.

$\rightarrow$ These exist. An integral curve through p having the largest possible interval of defⁿ is unique & is called the max int curve of X through p , denoted $\gamma_p: I_p \rightarrow M$.

¹⁵⁻⁴ → We call X complete if all integral curves of X have domain $= \mathbb{R}$.

- Such fields are important since they generate a global action of $\mathbb{R}$ on M

$$\mathbb{R} \times M \rightarrow M, (t, p) \mapsto \gamma_p(t).$$

The map $\Phi_X: \mathbb{R} \rightarrow \text{Diff}(M)$, $\Phi_X(t) = (p \mapsto \gamma_p(t))$ corresponds to this action.

- Writing φ_t for $\Phi_X(t)$, we see

$$\varphi_s \circ \varphi_t = \varphi_{s+t} \quad \forall s, t \in \mathbb{R}.$$

Flows! Given $X \in \mathcal{X}(M)$, $p \in M$; $\exists \epsilon > 0$ and $p \in U \subseteq M$, U open, a! smooth map

$$F: (-\epsilon, \epsilon) \times U \rightarrow M \text{ with } F(0, x) = x \\ \forall x \in U; \frac{d}{dt}(F(x, t)) = X(F(x, t)) \quad \forall t \in (-\epsilon, \epsilon), x \in U.$$

So the existence & uniqueness theorem gives a! family of integral curves of X on a nbd U of p , having the same domain $I = (-\epsilon, \epsilon)$; $\gamma_p(t) = F(t, p) \neq \varphi_t(p)$.

15-5 • X complete gives $\{\varphi_t\}_{t \in \mathbb{R}}$. This is
 call- $\mathcal{L}$ the 1-param. group of diffeoms assoc.
 to X ; $\varphi_t(p) := \sigma_p(t) = F(t, p)$.

When X is not nec. complete, we still
 get a 1-param. family of local diffeoms:

→ A local 1-param family of local diffeoms
 is a collection $\{(U_\alpha, \varphi_t^\alpha, \epsilon_\alpha)\}_\alpha$ s.t.

(i) U_α are open, (ii) $\bigcup_\alpha U_\alpha = M$

(iii) $\epsilon_\alpha > 0 \forall \alpha$; domain $\varphi_t^\alpha \supseteq U_\alpha$ and
 the map $(t, z) \mapsto \varphi_t^\alpha(z)$ is smooth, for
 $z \in U_\alpha, t \in (-\epsilon_\alpha, \epsilon_\alpha)$.

(iv) φ_t^α & φ_t^β agree on $\text{dom}(\varphi_t^\alpha) \cap \text{dom}(\varphi_t^\beta)$
 & t with $|t| < \min\{\epsilon_\alpha, \epsilon_\beta\}$.

(v) for $t, s \in (-\epsilon_\alpha, \epsilon_\alpha)$ with $t+s \in (-\epsilon_\alpha, \epsilon_\alpha)$,
 $\varphi_t^\alpha \circ \varphi_s^\alpha$ is defined on an open set $\supseteq U_\alpha$

& $\varphi_t^\alpha \circ \varphi_s^\alpha = \varphi_{t+s}^\alpha$ on U_α .

→ Any local 1-param. family is generated by
 a vector field, i.e. its local flow gives the
 1-param. family; $X(p)(t) = \frac{d}{dt}|_{t=0} f \circ \varphi_t^\alpha, p \in M$.

¹⁵ Sufficient Condⁿ for completeness: Let $X \in \mathcal{X}(M)$ be s.t. it admits a local 1-param family of diffeoms $\{(U_\alpha, \varphi_t^\alpha, \epsilon_\alpha)_\alpha\}$ with $\inf_\alpha (\epsilon_\alpha) > 0$. Then X is complete.

$\Rightarrow$ Vector fields on M are complete if M is compact

• G a Lie group, $X \in \mathfrak{g}$, then X is complete.

Exponential map: Let M be smooth, $X \in \mathcal{X}(M)$ be complete & $\{\varphi_t\}$ be the 1-param group assoc. to X . The exponential map of X is $\text{Exp}_X: M \rightarrow M$, $\text{Exp}_X(p) := \varphi_1(p) = \gamma_p(1)$.

Examples: 1. $A \in M_n(\mathbb{R})$, $A = (a_{ij})$. Let $\hat{A} \in \mathcal{X}(\mathbb{R}^n)$, $\hat{A} = \sum_{i,j} a_{ij} x_j \frac{\partial}{\partial x_i}$.

Then $\text{Exp}_{\hat{A}}(p) = e^{\hat{A}} \cdot p$ (see lect. 14)

2. If G be a Lie group, any $X \in \mathfrak{g}$ is complete, Exp_X is thus defined. Define

$$\exp(X) := \text{Exp}_X(e) = \varphi_1(e) = \gamma_e(1)$$

$$\exp(tX) = \varphi_t(e); \quad \{\varphi_t\} \text{ is the 1-param}$$

group assoc. to X . The map $\mathfrak{g} \xrightarrow{\exp} G$

15.7 is called the exponential map of G .

$$\rightarrow \text{Exp}_x(g) = L_g(\exp(x)), \quad \forall g \in G. \quad (*)$$

$$\text{For } G = GL_n(\mathbb{R}), \quad \exp(tA) = e^{tA}.$$

$\rightarrow$ For $X \in \mathfrak{g}$, the flow of X is given by $F_x(t, g) = g \exp(tx)$.

- If G is a Lie group, then the map $\mathbb{R} \rightarrow G, t \mapsto \exp(tx)$ is the maximal integral curve of X , passing through e .

Prf! We have, for $g \in G, \varphi_t(g) = \sigma_g(t)$
 $= F_x(t, g) = g \exp(tx).$

Hence $t \mapsto \exp(tx)$ is the (!) max integral curve of X through e . $\square$

Some properties of exp:

Lemma: $\exp((s+t)x) = \exp(sx) \cdot \exp(tx) \quad \forall s, t \in \mathbb{R}, X \in \mathfrak{g}.$

Proof! For $g \in G, X \in \mathfrak{g}, t \in \mathbb{R}, h \in G$

$$(L_g \text{Exp}_{tx} L_g^{-1})(h) = L_g \text{Exp}_{tx}(\tilde{g}h) = L_g L_{\tilde{g}h}^{-1}(\exp(tx)) \\ = L_h(\exp tx) = \text{Exp}_{tx}(h)$$

(by (*)). Hence $L_g \text{Exp}_{tx} = \text{Exp}_{tx} L_g$.

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Now

We have, for $g, h \in G$,

$$\exp((s+t)x) =$$

$$(L_g \exp_{tx} L_g^{-1})(h) = L_g \exp_{tx}(\bar{g}h) = L_g L_{\bar{g}h}(\exp(tx))$$

by (*).

$$= L_h \exp(tx)$$

$$= \exp_{tx}(h)$$

$$\therefore L_g \exp_{tx} = \exp_{tx} L_g.$$

$$\rightarrow \exp((s+t)x) = \varphi_{s+t}(e) = \varphi_s(\varphi_t(e)). \text{ And}$$

$$\varphi_s(\varphi_t(e)) = \varphi_s(L_{\varphi_t(e)}(e)) = \gamma_{\varphi_t(e)}(s)$$

$$= \exp((t+s)x) = \varphi_t(e) \underbrace{\exp(sx)}_{//} \text{ by (*)}$$

$$= \varphi_t(e) \varphi_s(e)$$

$$= \exp(tx) \exp(sx).$$



$\therefore \exp: \mathbb{R} \rightarrow G$ is a Lie group homom.

• Any Lie group map $\varphi: \mathbb{R} \rightarrow G$ is also called a 1-parameter subgroup of G .

$\rightarrow \exp: \mathfrak{g} \rightarrow G$ is a local diffeom around $0 \in \mathfrak{g}$. [See Kum; 2.8.28, follows from $\exp$ is smooth]

15.9. Grant $\exp: \mathfrak{g} \rightarrow G$ is smooth. Enough to prove $D(\exp)(0)$ is bijective. Let $X \in \mathfrak{g} \equiv T_e G$. Consider the curve $t \mapsto tX$ in $\mathfrak{g}$. This has tangent X at 0. Consider the image of this curve under $\exp$, i.e. $t \mapsto \exp(tX)$; this has tangent X at e . This shows $D(\exp)(0): \mathfrak{g} \rightarrow T_e G$ is bijective etc. $\square$

→ Let $\varphi: G \rightarrow H$ be a homomorphism of Lie groups. Then the diagram

$$\begin{array}{ccc} G & \xrightarrow{\varphi} & H \\ \uparrow \exp & & \uparrow \exp \\ \mathfrak{g} & \xrightarrow{d\varphi} & \mathfrak{h} \end{array}$$

Commutates, i.e.
 $\exp(d\varphi(x)) = \varphi(\exp(x))$
 $\forall x \in \mathfrak{g}$.

Pf. Consider the curves $t \mapsto \varphi(\exp(tx))$ & $t \mapsto \exp t(d\varphi(x))$. These are both integral curves for $d\varphi(x)$, through $e \therefore$ are equal. $\square$

→ Any one parameter subgroup $\varphi: \mathbb{R} \rightarrow G$ comes from some $X \in \mathfrak{g}$. More precisely, $\exists X \in \mathfrak{g}$ s.t. $\varphi(t) = \text{Exp}_{tx}(e)$.

B. Math (Hons.) III Year 2021-22
II Semester
ATTENDANCE SHEET

Course : Differential Geometry II
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