

Lecture-3

Calculus contd :- The class C^r, C^∞ etc. We saw that the existence and continuity of the partial derivatives of a function f on an open $U \subseteq \mathbb{R}^n$ implies differentiability of f at all points of U ; If $f: U \rightarrow \mathbb{R}^m$ is differentiable on U , we have $Df: U \rightarrow \text{Hom}_{\mathbb{R}}(\mathbb{R}^n, \mathbb{R}^m)$ $a \mapsto Df(a)$. We identify $\text{Hom}_{\mathbb{R}}(\mathbb{R}^n, \mathbb{R}^m)$ with the Euclidean space $\mathbb{R}^{mn}$ as usual. We say f is of class C^1 or f is C^1 if the map $a \mapsto Df(a)$ as above is continuous. Inductively, we define f to be C^r if Df is of class C^{r-1} ($C^0 \equiv$ continuous maps).

→ If f is $C^r \forall r \geq 1$, we say f is C^∞ or smooth.

Exercise :- $f \in C^r \Rightarrow$ all mixed partials

$$D^\alpha f_i := \frac{\partial^{i_1} \partial^{i_2} \cdots \partial^{i_n}}{\partial x_1^{i_1} \partial x_2^{i_2} \cdots \partial x_n^{i_n}} f_i \text{ exist and are}$$

Continuous $\forall 1 \leq i \leq m \quad \Delta \forall \alpha = (i_1, \dots, i_n)$

with $|\alpha| := \sum_j i_j \leq r$; Conversely this $\Rightarrow f \in C^r$.

Diffeomorphisms :- Fix $1 \leq r \leq \infty$. A C^r map

$f: U \rightarrow V$, $U \subseteq \mathbb{R}^n$, $V \subseteq \mathbb{R}^m$, open, is called a C^r -diffeomorphism if $\exists$ a C^r map $g: V \rightarrow U$ such that $g \circ f = 1_U$, $f \circ g = 1_V$.

A C^∞ -diffeomorphism is called smooth. When $r=0$, the notion simply means f is a homeomorphism.

→ If $f: U \rightarrow V$ is a C^r diffeomorphism, then the Jacobian matrix of f is invertible ($r \geq 1$) pointwise (why?). Note that if $\exists$ a C^r diffeomorphism $U \rightarrow V$, then $n=m$. This also holds when $r=0$. This follows from "Brouwer's invariance of domain" theorem from algebraic topology.

Exercise :- Let $r \geq 1$ and $f \in C^r; U \rightarrow V$ and assume f is a C^1 -diffeomorphism. Then f is a C^r -diffeomorphism.

Local diffeomorphisms :- Let $U \subseteq \mathbb{R}^n$ open & $f: U \rightarrow \mathbb{R}^n$ be a C^r map. We call f a C^r -local diffeomorphism at $p \in U$ if $\exists$ an open nbhd W of p such that $f|_W: W \rightarrow f(W)$ is a diffeomorphism.

$z \mapsto e^z$ is a C^r -diffeom.

Remark: If f is a C^r -local diffeom for all $p \in U$, then also f has invertible Jacobian at all $p \in U$; here $r \geq 1$.

Example:- Consider $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by
 $(x, y) \mapsto (e^x \cos y, e^x \sin y)$.

(Equivalently $z \mapsto e^z: \mathbb{C} \rightarrow \mathbb{C}$). This is not a diffeom (Why?), but f restricted to any open strip $\mathbb{R} \times (b, b+2\pi)$ is a diffeom. Note that f maps this open strip (diffeomorphically) to the half-slit plane, i.e. $\mathbb{R}^2$ minus the half ray $\{(\lambda \cos b, \lambda \sin b); \lambda \geq 0\}$ (picture this?).

Exercise:- $U, V \subseteq \mathbb{R}^n$ be open, $f: U \rightarrow V$ a smooth bijection. Then f is a smooth diffeo $\Leftrightarrow f$ is a C^1 -local diffeo at all $p \in U$.

Inverse function theorem:- Let $U \subseteq \mathbb{R}^n$ be open and $f: U \rightarrow \mathbb{R}^n$ be C^r , $r \geq 1$. Let $p \in U$ and $Df(p)$ be invertible. Then f is $\rightarrow$

3-4 a C^r -local diffeom at p .

(Sketch of) proof :- First suppose f is an

affine map, i.e. $f(x) = Ax + v$ where $A: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is linear and $v \in \mathbb{R}^n$ is a fixed vector. Then, for $w, z \in U$, we have

$$f(w) - f(z) = Aw - Az = Df(z)(w - z) \quad (?).$$

Hence if $Df(z) = A$ is invertible and we wish to have the inverse image w of some $y = f(w)$, we can solve it as

$$\boxed{w = z - Df(z)^{-1}(f(z) - y)} \quad \sim \#$$

→ Let f be any map satisfying the hypothesis.

Using $\varphi(x) := Df(p)^{-1}(f(x+p) - f(p)): U \rightarrow \mathbb{R}^n$

we may assume (without loss of generality)

that $p=0$, $f(0)=0$ and $Df(0) = I_{\mathbb{R}^n}$.

→ Let $B = \overline{B(0, \delta)}$ be the closed ball of radius δ around the origin s.t. $\overline{B} \subseteq U$ (δ to be chosen suitably). For $y \in \mathbb{R}^n$

define $T_y: B \rightarrow \mathbb{R}^n$ by $z \mapsto z - (f(z) - y)$,

motivated by $\#$, so that this would give the inverse image of y when f is affine.

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Lemma-1 :- Let $U \subseteq \mathbb{R}^n$ be an open ball around the origin, $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be C^1 and suppose $\exists M > 0$ such that $|\partial f_i / \partial x_j (x)| \leq M$
 $\forall x \in U$. Then $\|f(x) - f(y)\| \leq n^2 M \|x - y\|$
 $\forall x, y \in U$.

Lemma-2 (Contraction mapping principle).
Let (X, d) be a complete metric space,
 $f: X \rightarrow X$ be a contraction, i.e., $d(f(x), f(y))$
 $\leq \lambda d(x, y)$ for some $0 \leq \lambda < 1, \forall x, y \in X$.
Then $\exists!$ $x \in X$ such that $f(x) = x$.

The function $g: \mathbb{R}^n \rightarrow \mathbb{R}^n, g(x) = x - f(x)$.
Then $g(0) = 0$ & $Dg(0) = 0$; g is C^1
and $\exists \delta > 0$ s.t.

$$\left| \frac{\partial g_i}{\partial x_j}(x) - \frac{\partial g_i}{\partial x_j}(0) \right| < \frac{1}{2n^2} \quad \forall x \in B(0, \delta)$$

$$\left| \frac{\partial g_i}{\partial x_j}(x) \right| \quad \text{Use Lemma-1}$$

& put $y=0$ to get $\|g(x)\| < \frac{\|x\|}{2} \quad \forall x \in B(0, \delta)$

$$\therefore g(B(0, \delta)) \subseteq B(0, \delta/2).$$

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$$\rightarrow T_y(x) = x - (f(x) - y) = y + g(x).$$

$$\Rightarrow \|T_y(x)\| \leq \|y\| + \|g(x)\|. \text{ Hence}$$

$$\text{for } y \in \overline{B(0, \delta/2)}, \|T_y(x)\| \leq \delta/2 + \delta/2 = \delta$$

$$\text{and so } T_y: \overline{B(0, \delta)} \rightarrow \overline{B(0, \delta)} \text{ and}$$

$$T_y(x) = x \Leftrightarrow y + x - f(x) = x \Leftrightarrow y = f(x).$$

$$\rightarrow f \text{ is 1-1 on } \overline{B(0, \delta)} \Leftrightarrow T_y \text{ has a!}$$

$$\text{fix-}\omega \text{ point in } \overline{B(0, \delta)}.$$

$$\rightarrow \text{For } y \in \overline{B(0, \delta/2)}, T_y \text{ is a contraction.}$$

$$\rightarrow \text{Hence } f \text{ is 1-1 on } \overline{B(0, \delta)}.$$

$$\rightarrow f(\underbrace{B(0, \delta/4)}_W) \text{ is open; } \tilde{f}: f(W) \rightarrow W$$

$$\text{is smooth: } \forall p \in W, f \in C^1 \Rightarrow$$

$$f(x) - f(p) = Df(p)(x-p) + e(x, p),$$

$$\text{Where } \lim_{x \rightarrow p} \frac{e(x, p)}{\|x-p\|} = 0. \quad (*)$$

$$\text{Hence if } y = f(x) \text{ \& } q = f(p), A = Df(p)^{-1},$$

$$\text{we have } \rightsquigarrow$$

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$$A(y-q) = \tilde{f}'(y) - \tilde{f}'(q) + A \in (\tilde{f}'(y), \tilde{f}'(q)).$$

$$\text{Hence } \tilde{f}'(y) - \tilde{f}'(q) = A(y-q) + \epsilon'(y, q).$$

$$\text{Now } \lim_{y \rightarrow q} \frac{\epsilon'(y, q)}{\|y - q\|} = -A \lim_{y \rightarrow q} \underbrace{\epsilon(\tilde{f}'(y), \tilde{f}'(q))}_{\rightarrow 0(?)} \text{ and}$$

Hence $\tilde{f}'$ is differentiable $\forall p \in W$ &

$$(D\tilde{f}')(p) = (Df)(\tilde{f}'(p))^{-1} \quad \square$$

- The IFT controls the local behaviour of a function, i.e. says what happens in a nbhd of a point, from the information on its derivative at that point.
- It is possible (?) for a map to be a local diffeomorphism at each point without being a global diffeomorphism. However any $f: \mathbb{R} \rightarrow \mathbb{R}$ that is a C^r -local diffeomorphism at each point (here $r \geq 1$) is indeed a global diffeomorphism (?).

Exercise 1. In general $C^{r+1} \subsetneq C^r$.

2. $f: \mathbb{R} \rightarrow \mathbb{R}$, $f(x) = \frac{x}{2} + x^2 \sin \frac{1}{x}$ has non-vanishing derivative $Df(0) = 1/2$ at $x=0$. $\rightarrow$

38 However, f is not a diffeom in any nbhd of $x=0$; in fact f even fails to be 1-1 in any nbhd of 0. This shows that f being at least C^1 in IFT cannot be relaxed.

One uses IFT to prove the
Implicit function Theorem: Let $f: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}^m$ be continuously differentiable in an open set containing $(a, b) \in \mathbb{R}^n \times \mathbb{R}^m$ and $f(a, b) = 0$. Let M be the $m \times m$ matrix $\left(\frac{\partial f_i}{\partial x_{n+j}}(a, b) \right)_{1 \leq i, j \leq m}$. If $\det M \neq 0$, there exists an open set $V \subseteq \mathbb{R}^n$, $a \in V$; an open $W \subseteq \mathbb{R}^m$, $b \in W$, such that for every $x \in V$, $\exists!$ $g(x) \in W$ (with $g(a) = b$), $f(x, g(x)) = 0 \forall x \in V$. The function $g: V \rightarrow W$ thus defined is differentiable. $\square$

In the next class, we'll see some applications of these results. It cannot be emphasized enough that these results are very fundamental to differential geometry.

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