

Lecture - 4

Remarks on the Implicit Function Theorem :- To understand what the above achieves, consider a relation, say in $\mathbb{R}^2$, given as $F(x, y) = 0$. Such a "rel" does not necessarily represent a function (of say x), i.e. this may not lead to a solution of the form $y = f(x)$ for a function f (e.g. $F(x, y) = x^2 + y^2 - 3$). One naturally asks: When, a "rel" $F(x, y) = 0$, represents a function, or equivalently, when can the eqⁿ $F(x, y) = 0$ be solved explicitly for y in terms of x , giving a! solution?

The Implicit function theorem tells us that 'locally' this can be achieved (for good F), i.e. given a point (x_0, y_0) with $F(x_0, y_0) = 0$, under 'certain conditions', $\exists$ a nbd of (x_0, y_0) such that in this nbd, $F(x, y) = 0$ yields a functional solⁿ $y = f(x)$. The conditions stipulate that F & $\partial F / \partial y$ be continuous in some nbd of (x_0, y_0) and $\frac{\partial F}{\partial y}(x_0, y_0) \neq 0$.

→ More generally: let $f: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}^m$ be cont. diff. in an open nbd of $(a, b) \in \mathbb{R}^n \times \mathbb{R}^m$, $f((a, b)) = 0$. Assume that the $m \times m$ matrix $\frac{\partial f}{\partial y}(a, b) \neq 0$.

4-2 $\left(\frac{\partial f_i}{\partial x_{n+j}}(a,b) \right)_{1 \leq i,j \leq m}$ is invertible. Then

$\exists$ a nbd $A \times B \subseteq \mathbb{R}^n \times \mathbb{R}^m$ of (a,b) and a diff. function $g: A \rightarrow B$, $g(a) = b$, s.t.
 $f(x, g(x)) = 0 \quad \forall x \in A.$ ⊗

Submersion: A C^r -map, for $r \geq 1$, $f: U \rightarrow \mathbb{R}^m$ is a submersion at $a \in U$ (open) if $Df(a)$ is surjective. (This $\Rightarrow n \geq m$ and Jacobian of f at a has rank m). $U, \mathbb{R}^n$

Immersion: Let $r \geq 1$. A C^r -map $f: U \rightarrow \mathbb{R}^m$ is a C^r immersion at $a \in U$ if $Df(a)$ is injective; (so in this case $n \leq m$ and the Jacobian of f at a has rank n).

Rank theorem: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be cont. diff. in an open set $\ni a$, $n \geq m$. If $f(a) = 0$ and the $m \times n$ matrix $\left(\frac{\partial f_i}{\partial x_j}(a) \right)$ has rank m ; then $\exists$ an open set $A \subseteq \mathbb{R}^n$ and a diff. funcⁿ $h: A \rightarrow \mathbb{R}^n$ with a diff inverse (i.e. h is a diffeom) s.t.
 $f \circ h(x_1, \dots, x_n) = (x_{n-m+1}, \dots, x_n).$ ⊗

Hence one can modify the coordinates around the point a by the function h to get a simpler form for f locally.

Level sets: Let $U \subseteq \mathbb{R}^{n+1} = \mathbb{R}^n \times \mathbb{R}$ be open & $f: U \rightarrow \mathbb{R}$ be smooth. Let $c \in \mathbb{R}$ be such that for $S = f^{-1}(c)$, $(\nabla f)(p) \neq 0$ $\forall p \in S$ (we assume such c exists for f). We then call S a hypersurface in $\mathbb{R}^{n+1}$.

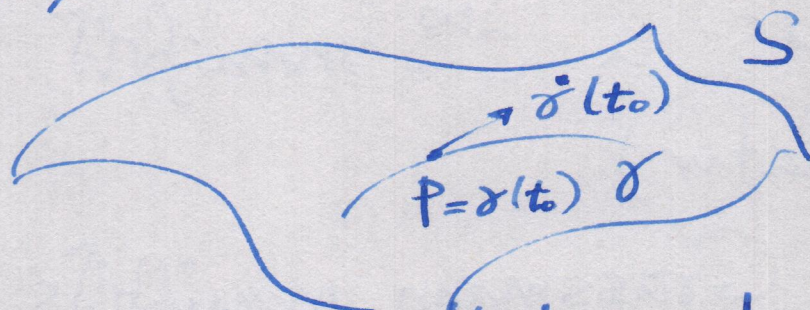
A parametrized curve in $\mathbb{R}^{n+1}$ is a smooth function $\gamma: I \rightarrow \mathbb{R}^{n+1}$, I some open interval in $\mathbb{R}$; so $\gamma(t) = (\gamma_1(t), \dots, \gamma_{n+1}(t))$, $\gamma_i: I \rightarrow \mathbb{R}$ are smooth. Denote

$$\dot{\gamma}(t) := (\dot{\gamma}_1(t), \dots, \dot{\gamma}_{n+1}(t)), \text{ where } \dot{\gamma}_i(t) = \frac{d}{dt} \gamma_i(t). \text{ When } \dot{\gamma}(t_0) \neq 0, \text{ we}$$

call $\dot{\gamma}(t_0)$ the tangent vector to $\gamma(t)$ at the point $\gamma(t_0)$. (justify this?).

We define, for S as above $\leadsto$

a tangent vector to S at $p \in S$ is, by defⁿ, $\dot{\gamma}(t_0)$ for some curve $\gamma \in S$, where $p = \gamma(t_0)$, i.e. γ lies on S and passes through p .



We denote $T_p(S)$ = set of all tangent vectors to S at p . We first observe

Lemma :- The gradient of f at p , i.e. $\nabla f(p)$ ($\equiv Df(p)$) is orthogonal to $T_p(S)$.

Proof :- Let $v \in T_p(S)$. Then $v = \dot{\gamma}(t_0)$ for some $\gamma: I \rightarrow S = f^{-1}(c)$. Therefore $f(\gamma(t)) = c \quad \forall t \in I$. Differentiating we get $\frac{d}{dt}(f \circ \gamma) = 0$, so $Df(\gamma(t_0)) \cdot \dot{\gamma}(t_0) = 0$

$$= \nabla f(p) \cdot \dot{\gamma}(t_0) = 0$$

$$\langle \nabla f(p), \dot{\gamma}(t_0) \rangle = 0$$



An application of the Implicit funcⁿ thm: $\rightarrow$

4-5 Generalized level sets : We'll discuss level sets for $f: U \subseteq \mathbb{R}^{n+k} \rightarrow \mathbb{R}^k$, for smooth f and define the tangent space $T_p S$ of $S = f^{-1}(0)$ at $p \in S$ as the set of all vectors $v \in \mathbb{R}^{n+k}$ such that $v = \dot{\gamma}(0)$ for a smooth $\gamma: I \rightarrow S$, $\gamma(0) = p$, $0 \in I$. We sketch a proof of

Theorem : Let $f: U \subseteq \mathbb{R}^{n+k} \rightarrow \mathbb{R}^k$ be C^1 . Assume $S := f^{-1}(0) \neq \emptyset$ and $\forall p \in S$, $Df(p)$ has rank k . Then $T_p(S) = \text{Ker } Df(p)$. In particular $T_p(S)$ is an n -dim'l vector space $\mathbb{R}$.

Proof (Sketch) : - Just like the case $k=1$,

$T_p(S) \subseteq \text{Ker}(Df(p))$ (Chain rule).

• Conversely, let $w \in \mathbb{R}^{n+k}$ be such that $Df(p)(w) = 0$. Since $Df(p)$ has rank k , by composing f with a suitable permutation, we may assume $\left(\frac{\partial f_i}{\partial x_{n+j}} \right)_{1 \leq i, j \leq k}$ is invertible.



4th b. Write any $z \in U \subseteq \mathbb{R}^{n+k}$ as $z = (x, y)$,
 $x \in \mathbb{R}^n$, $y \in \mathbb{R}^k$; $p = (a, b)$, $\omega = (u, v)$.

Let $G: U \subseteq \mathbb{R}^{n+k} \rightarrow \mathbb{R}^{n+k}$ be defined by

$$G(x, y) := (x, f(x, y)). \text{ Then}$$

- $DG(p)$ is invertible (?). So $\exists$
nbds U_1 of p in $\mathbb{R}^{n+k}$ and V of a in $\mathbb{R}^n$
and a C^1 map $h: V \rightarrow \mathbb{R}^k$ such that

- $h(a) = b$; $\{(x, y) \in U_1 \mid f(x, y) = 0\}$
 $= \{(x, h(x)) \mid x \in V\}$.

- Consider $\gamma(t) := a + tu$ ($\omega = (u, v)$).

$\Rightarrow \gamma(t) \in V$ for sufficiently small t .

- $C(t) := G^{-1}(\gamma(t), 0)$. Then C is
 C^1 as G is; $C(0) = \bar{G}^{-1}(\gamma(0), 0)$
 $= \bar{G}^{-1}(a, 0) = (a, b) = p$.

- $\dot{C}(0) = \omega$. This follows from the
computation $DG(p)(\omega = (u, v)) = (u, 0)$.



4-7. Given $f: \mathbb{R}^{n+k} \rightarrow \mathbb{R}^k$ as in the theorem and $S = f^{-1}(0)$ the corresponding level set, for $p \in S$, $Df(p): \mathbb{R}^{n+k} \rightarrow \mathbb{R}^k$ (rank k) $\Rightarrow \ker(Df(p)) = T_p(S)$.

When $k=1$, we have $T_p(S) = \nabla f(p)^\perp \subseteq \mathbb{R}^{n+1}$ and $\nabla f(p)$ is the normal to the hypersurface S , $\forall p \in S$.

Towards a differentiable structure on S :

Let $S = f^{-1}(0)$, $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ a C^1 -map with $\nabla f(p) \neq 0 \forall p \in S$ (the rank condⁿ).

Fix $p_0 = (a_1, \dots, a_{n+1}) \in S$, so $\nabla f(p_0) \neq 0$.

Let $Q_0 = (a_1, \dots, a_n) \in \mathbb{R}^n$ be the projⁿ of p_0 onto $\mathbb{R}^n$. By the Implicit funcⁿ thm, $\exists$

an open set $V_0 \ni Q_0$, an interval $(a_{n+1} - \delta, a_{n+1} + \delta)$ and a C^1 -map g on V_0

such that $f(x_1, \dots, x_n, g(x_1, \dots, x_n)) = 0$

in $V_0 \rightsquigarrow$

4-8. $a_{n+1} = g(a_1, \dots, a_n)$, $|a_{n+1} - g(a_1, \dots, a_n)| < \delta$
in V_0 .

• Any solⁿ $(x_1, \dots, x_{n+1}) \in V_0 \times (a_{n+1} - \delta, a_{n+1} + \delta)$
of the eqⁿ $f(x_1, \dots, x_{n+1}) = 0$ is of
the form $x_{n+1} = g(x_1, \dots, x_n)$.

Let $U_0 = S \cap V_0 \times (a_{n+1} - \delta, a_{n+1} + \delta)$. Then

$p_0 \in U_0$ and the restriction of the
Projection: $\mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$ to U_0 gives

$$\varphi_0: U_0 \rightarrow V_0, \varphi_0(x_1, \dots, x_n, x_{n+1}) = (x_1, \dots, x_n) \in V_0,$$

with $\varphi_0^{-1}(x_1, \dots, x_n) = (x_1, \dots, x_n, g(x_1, \dots, x_n))$.

• φ_0 is a diffeom.

Thm: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be smooth, $S = f^{-1}(0) \neq \emptyset$,
the Jacobian of f has rank m at all pts
of U . Then every point of S has an
open nbd diffeomorphic to an open
subset of $\mathbb{R}^{n-m}$.

Proof is an exercise for you. Next
class: important examples of S as
above.

