

8-5 More generally, when A is a commutative ring and M an A -module, we define $\delta: A \rightarrow M$ as above. The directional derivative operators, by the lemma, are precisely the 'point derivations' on $C^\infty(p)$, i.e. those satisfying the product formula $\delta(fg) = f(p)\delta(g) + \delta(f)g(p)$. Hence we have

$$\begin{aligned} T_p(\mathbb{R}^n) &\equiv T_p(U) = \left\{ [\gamma] \mid \gamma \subseteq U \text{ smooth, } \gamma(0) = p \right\} \frac{d}{dt} \bigg|_{t=0} \\ &= \{ \delta \mid \delta \text{ a point derivation on } C^\infty(p) \}. \end{aligned}$$

Remarks: (i) In finding/solving for ' v ' for a given point derivation δ , we need in (*) that f be smooth; if f were only C^1 e.g. then the g_i 's in (*) may be only continuous and then δ cannot be applied.

(ii) Given $f: U \rightarrow \mathbb{R}^m$, $p \in U$, $f = (f_1, \dots, f_m)$,

$f_i = \alpha_i \circ f$, we have

$Df(p): \mathbb{R}^n \rightarrow \mathbb{R}^m$. We may now

think of $\mathbb{R}^n = T_p(U)$, $\mathbb{R}^m = T_{f(p)}(\mathbb{R}^m)$

3-6 and identify $Df(p)(v) = (Df_1(p)(v), \dots, Df_m(p)(v))$ as a column vector and hence $Df(p)(v)$

$$= \begin{pmatrix} \frac{\partial f_1}{\partial x_1}|_p & \dots & \frac{\partial f_1}{\partial x_n}|_p \\ \vdots & & \vdots \\ \frac{\partial f_m}{\partial x_1}|_p & \dots & \frac{\partial f_m}{\partial x_n}|_p \end{pmatrix} \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}.$$

Tangent space to a manifold: - Let now M be a smooth manifold, $p \in M$. Let $C^\infty(p) =$ Set of smooth $\mathbb{R}$ -valued functions defined in a nbd of p ; i.e. $f: U_f \rightarrow \mathbb{R}$ is smooth on the open set $U_f \subseteq M$.

Def: - A tangent vector v at $p \in M$ is a point derivation of $C^\infty(p)$, i.e. $v: C^\infty(p) \rightarrow \mathbb{R}$ is $\mathbb{R}$ -linear and $v(fg) = f(p)v(g) + v(f)g(p)$, $f, g \in C^\infty(p)$.

We denote the $\mathbb{R}$ -vector space of all tangent vectors to M at p by $T_p(M)$.

Some elements of $T_p(M)$: - Let (U, φ) be a coordinate chart around p and $\varphi(p) = 0 \in \mathbb{R}^n$. Let x_i ($1 \leq i \leq n$) denote the coordinate functions on U and u_i be the coordinates

γ^{-1} in $\mathbb{R}^n$. Then, for $f \in C^\infty(p)$, define

$$\begin{aligned}\frac{\partial}{\partial x_i} \Big|_p (f) &:= \frac{\partial}{\partial u_i} (f \circ \varphi^{-1}) (0) \\ &= \frac{\partial}{\partial u_i} \Big|_0 (f \circ \varphi^{-1}).\end{aligned}$$

Then $\frac{\partial}{\partial x_i} \Big|_p \in T_p(M)$ (check this, easy!)

• When $f = x_i$, $\frac{\partial}{\partial x_i} \Big|_p (f) = \frac{\partial}{\partial u_i} (\underbrace{x_i \circ \varphi^{-1}}_{u_i}) (0)$
 $= \frac{\partial}{\partial u_i} (u_i) (0) = 1.$

Derivatives of curves on M :- Let $\gamma: (-\epsilon, \epsilon) \rightarrow M$ be a smooth curve through p , i.e. $\gamma(0) = p$.

Define $\dot{\gamma}(0)$ by the point derivation

$$\dot{\gamma}(0)(f) := \frac{d}{dt} (f \circ \gamma) (0) =: \frac{d}{dt} \Big|_{t=0} (f \circ \gamma).$$

Then

• $\dot{\gamma}(0)(f+g) = \dot{\gamma}(0)(f) + \dot{\gamma}(0)(g)$

• $\dot{\gamma}(0)(fg) = \frac{d}{dt} ((fg) \circ \gamma) (0)$

$$= f(p) (\dot{\gamma}(0)(g)) + (\dot{\gamma}(0)(f)) g(p)$$

as is easily checked (see Kumarisan).

Hence $\dot{\gamma}(0) \in T_p(M)$. We have $\leadsto$

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- Theorem :- Let M be a smooth manifold, $p \in M$ and (U, φ) be a chart around p , x_i the local coordinates on U , $1 \leq i \leq m = \dim M$.
- Let $v \in T_p(M)$. Then $v = \sum_i v(x_i) \frac{\partial}{\partial x_i} \Big|_p$
 - $\left\{ \frac{\partial}{\partial x_i} \Big|_p, 1 \leq i \leq m \right\}$ are lin. indep./ $\mathbb{R}$.
 - $\dim T_p M = m = \dim M$.

Proof :- Assume wlog that $\varphi(p) = 0$. Then $\varphi(U) \subseteq \mathbb{R}^m$ is an open set $\ni 0$ and $\bar{f} := f \circ \varphi^{-1} \in C^\infty(0)$.

Then the Taylor formula for $\bar{f}$ gives

$$(\#) \quad \bar{f}(x) = \bar{f}(0) + \sum_i u_i G_i(x), \text{ where}$$

$$G_i \text{ are smooth around } 0 \text{ \& } G_i(0) = \frac{\partial}{\partial u_i} \bar{f}(0).$$

Composing $(\#)$ by φ yields

$$(*) \quad f(x) = f(p) + \sum x_i g_i(x);$$

$$x_i = u_i \circ \varphi, \quad g_i = G_i \circ \varphi.$$

$$\text{Hence } v(f) = v(f(p)) + \sum_i [v(x_i) g_i(p) + x_i(p) v(g_i)].$$

We have $g_i(p)$

$$= G_i \circ \varphi(p) = G_i(0) = \frac{\partial}{\partial u_i} \Big|_0 (f) = \frac{\partial}{\partial u_i} \Big|_0 (f \circ \varphi^{-1}).$$

We defined $\frac{\partial}{\partial x_i} \Big|_p (f) := \frac{\partial}{\partial u_i} \Big|_0 (f \circ \varphi^{-1})$. Hence

$$g_i(p) = \frac{\partial}{\partial x_i} \Big|_p (f).$$



8-9. But $\nabla(f(p)) = 0 = \alpha_i(p)$ as $\varphi(p) = 0$. Hence

$$\nabla = \sum_i \nabla(\alpha_i) \frac{\partial}{\partial \alpha_i} \Big|_p.$$

[discuss the case of φ when $\varphi(p) \neq 0$]. $\square$

Linear independence of $\frac{\partial}{\partial \alpha_i} \Big|_p$: We have

already computed $\frac{\partial}{\partial \alpha_i} (\alpha_i) = 1$. We have

$$\frac{\partial}{\partial \alpha_i} \Big|_p (\alpha_j) = \frac{\partial}{\partial u_i} (\alpha_j \circ \varphi^{-1})(0) = \frac{\partial}{\partial u_i} (u_j)(0)$$

$$= \delta_{ij}. \text{ Hence } \left\{ \frac{\partial}{\partial \alpha_i} \Big|_p, 1 \leq i \leq m \right\} \text{ form}$$

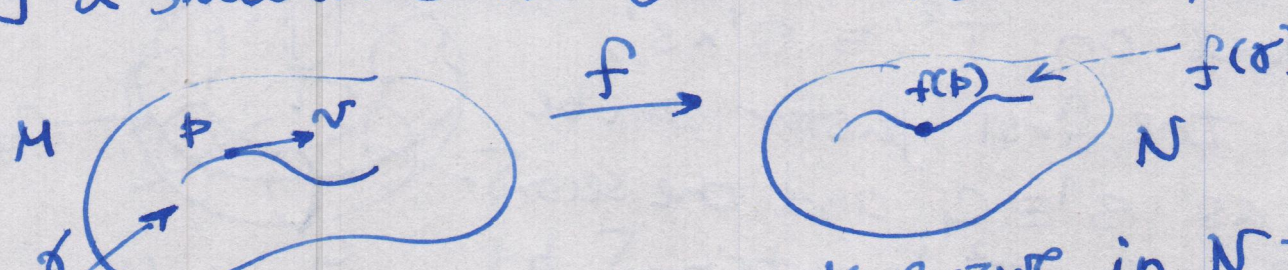
a basis of $T_p(M)$ and thus $\dim_{\mathbb{R}} T_p(M) = m$.

*Lemma: For any $v \in T_p(M)$, $\exists$ a smooth curve γ on M , $\gamma(0) = p$ & $\dot{\gamma}(0) = v$.

Proof: Class discussion exercise. $\square$

This Lemma allows us to identify $T_p(M)$ with the set of equivalence classes of smooth curves γ on M with $\gamma(0) = p$; under the equiv. $\gamma \sim \sigma$ if $\gamma(0) = \sigma(0) = p$ & $\dot{\gamma}(0) = \dot{\sigma}(0)$ as elements of $\text{Der}_{\mathbb{R}}(C^\infty(p), \mathbb{R}) = \text{point derivations on } C^\infty(p)$.

8-10 Derivatives of smooth maps: Let M, N be smooth manifolds of $\dim m, n$ resp, $f: M \rightarrow N$ be a smooth map. In analogy with the case of $M = U \subseteq \mathbb{R}^m$, $N = \mathbb{R}^n$, we would like the derivative of f at $p \in M$ to be a linear map $Df(p): T_p M \rightarrow T_{f(p)} N$. We use the earlier Lemma for this. Let $v \in T_p M$. Then $\exists$ a smooth curve γ on M , $\gamma(0) = p$, $\dot{\gamma}(0) = v$.

 Then $f \circ \gamma$ is a smooth curve in N through $f(p)$. We can therefore define

$Df(p)(v) := (f \circ \gamma)'(0)$. Since $f \circ \gamma$ is a smooth curve through $f(p)$ on N , $(f \circ \gamma)'(0) \in T_{f(p)}(N)$.

- $Df(p)(v)$ is well defined.

- $Df(p): T_p M \rightarrow T_{f(p)} N$ is a linear

map.

- $Df(p)(v)(g) = v(g \circ f)$, $g \in C^\infty(f(p))$.

These are left to you as exercises.

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