

∴ 2nd Class ∴

Brief Recap of last Class:

- Goal is to formalize the fundamental question in coding theory "How much redundancy do we need to correct certain amount of error."

- Formalized redundancy via $\text{Rate}(R) := \frac{k - \text{dimension}}{n \rightarrow \text{block length}}$

- Examples of two simple codes:

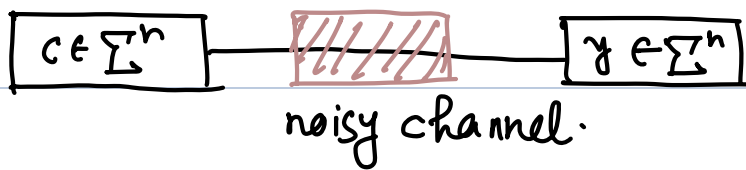
$$C_{\oplus} \text{ \& } C_{3,\text{rep}}$$

Formalizing Error Correction:

Encoding function: for any code $C \subseteq \Sigma^n$, the alternate view of C , $E: [C] \xrightarrow{\text{injective}} \Sigma^n$ is called encoding function.

Decoding function: $D: \Sigma^n \rightarrow [C]$

Recovers original message from corrupt received words $\Rightarrow$ Need to understand nature of errors & how it affects the received word.



Quantifying Errors via Hamming Distance:

Hamming Distance: $u, v \in \Sigma^n$, Hamming distance b/w u & v , $\Delta(u, v)$, is the no. of positions in which u & v differ. & relative Hamming distance, $\delta(u, v) = \frac{1}{n} \Delta(u, v) \in [0, 1]$

Example:

$$u = 0000, \quad v = 10001, \quad w = 01001 \in \{0, 1\}^5$$

$$\Delta(u, v) = \Delta(v, w) = 2 \quad \&$$

$$\delta(u, v) = \delta(v, w) = \frac{1}{2}$$

Hamming distance is a distance in a very formal mathematical sense: i.e., 1. $\Delta(x, y) \geq 0$.

2. $\Delta(x, y) = 0$ iff $x = y$

3. $\Delta(x, y) = \Delta(y, x)$

4. $\Delta(x, y) \leq \Delta(x, z) + \Delta(y, z)$ [Triangular inequality]

[Exercise].

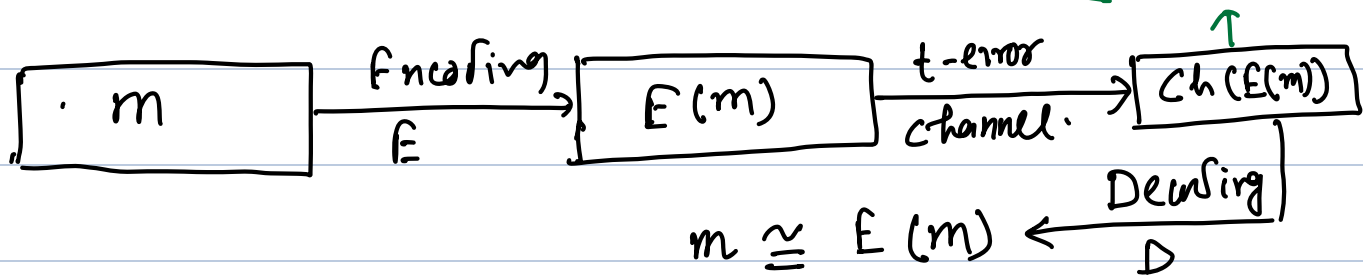
Quantifying error: hamming distance b/w received & transmitted words.

Formalizing performance of Error Correcting Codes:

t-Error Channel: An n -symbol t -error channel over the alphabet Σ is a function $ch: \Sigma^n \rightarrow \Sigma^n$ satisfies $\Delta(v, ch(v)) \leq t$ for $v \in \Sigma^n$.

Error correcting code: C is a t -error correcting code if $\exists D$ s.t. for every $m \in [C]$ & every t -error channel ch , $D(ch(E(m))) = m$

$\Delta(E(m), ch(E(m))) \leq t$



Example: a codeword $(0, 0, 0, 0)$ of 1-error correcting code. & transmitted. Then, the 1-error correcting code will decode it from any of the following received word.

$(0, 0, 0, 0), (1, 0, 0, 0), (0, 1, 0, 0), (0, 0, 1, 0), (0, 0, 0, 1)$.

Some weaker notation:

Error Detection code: C is t -error detecting code if $\exists$ a decoding procedure D s.t. $\forall$ message $m \in [C]$ & every received word v with $\Delta(v, E(m)) \leq t$, D outputs $\perp$ if $v \neq E(m)$

0 otherwise.

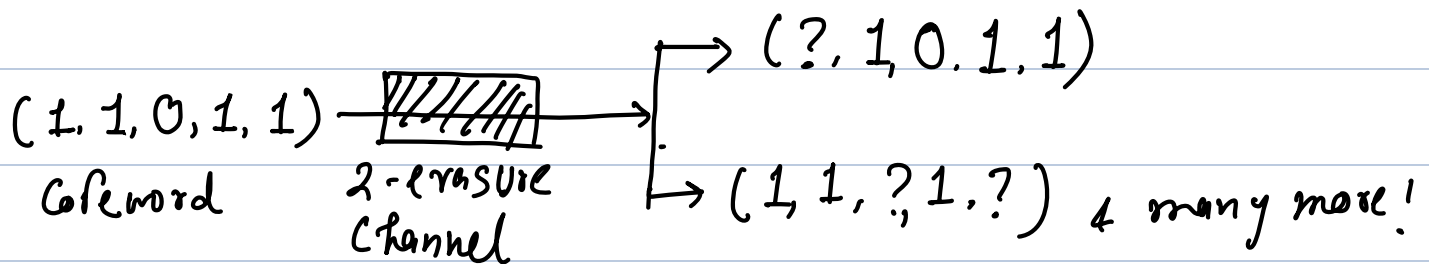
Another benign model of errors referred to as "erasures" a symbol is merely omitted from the transmission as opposed to being replaced by other symbol.

t-erasure channel: $ch: \Sigma^n \rightarrow (\Sigma \cup \{?\})^n$ s.t.

$$\forall v \in \Sigma^n, \Delta(v, ch(v)) \leq t$$

- if we see both $v, ch(v)$ is a string over $\Sigma \cup \{?\}$
then, $\forall i \in [n], v_i \neq ch(v)_i$, we have $ch(v)_i = ?$

Example:



Erasure Correcting Codes: Gde $C \subseteq \Sigma^n$ & $t \in \mathbb{N}$,

C is t -erasure correcting code if $\exists$ a decoding function D s.t. $\forall m \in \Sigma^n$, $\forall$ t -erasure channel ch
 $D(ch(E(m))) = E(m) \cong m$.

Error correction capabilities of $C_{\oplus}$ & $C_{3,rep}$:

$$C_{\oplus}: q=2, k=4, n=5, R=4/5$$

$$C_{3,rep}: q=2, k=4, n=12, R=1/3.$$

Error correction capability of $C_{3,rep}$:

- trivial decoding function:

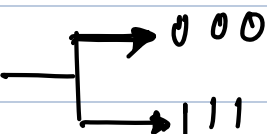
divide into four blocks (y_1, y_2, y_3, y_4)

each block 3-bits;

for block y_i , output 1 if 1 is the majority
0 otherwise.

Exercise: $C_{3,rep}$ 1-error correcting code.

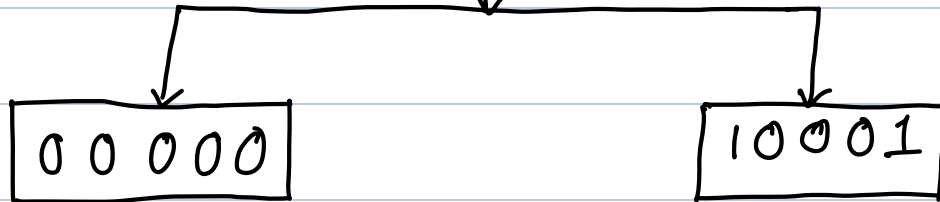
But it cannot correct two errors:

one received block: 101 

Pin-point: Can correct one error but not two or more!

Error correction capability of C_+ : Cannot even correct one error!

Example: Received word: $\boxed{10000}$
Possible transmitted word.



But, can detect on bit of error!

Any odd number of error, but not even number of errors!

Distance of a code:

- a parameter of code which captures its error correction capability.

Distance: For a code C , distance of C , $d(C) = \min_{c_1 \neq c_2 \in C} d(c_1, c_2)$.

Example: $d(C_{3, \text{rep}}) = 3$

$d(C_+) = 2$.

Formal connection b/w error-correction & distance:

Proposition: Given a code C , the following are equivalent.

1. $\text{dist}(C) \geq d$
2. If d is odd, C can correct $\frac{d-1}{2}$ errors.
3. C can detect $d-1$ errors
4. C can correct $d-1$ erasures.

Remark: for Property 2 for even d : can correct up to $\frac{d}{2}-1$ errors but may not correct $\frac{d}{2}$ errors. [Exercise]

Application: $C_{3\text{rep}}$ can correct up to 1 error

C_0 can detect up to 1 error, but cannot correct 1 error.

Proof Strategy: $P1 \Rightarrow P2, P3, P4$ & $\neg P1 \Rightarrow \neg P2, \neg P3, \neg P4$.

$P1 \Rightarrow P2, P3, P4$:

1. $P1 \Rightarrow P2$: Maximum likelihood decoding (MLD):

$$D_{\text{MLD}}: \Sigma^n \rightarrow C \text{ s.t.}$$

$$\forall y \in \Sigma^n, D_{\text{MLD}}(y) = \arg \min_{c' \in C} \Delta(c', y)$$

Naive Maximumlikelihood Decoder:

- Input: Received word $y \in \Sigma^n$
- Output: $D_{\text{MLD}}(y)$

1. Pick an arbitrary $c \in C$ & $z \leftarrow c$
2. $\forall c' \in C$
3. if $\Delta(c', y) < \Delta(z, y)$ then
4. $z \leftarrow c'$
5. Return z .

Convince the above algorithm computes D_{MLD} .

Let $d = 2t + 1$.

Goal: $\exists$ a decoder D s.t. for at most t errors, it outputs the transmitted message!

Claim: M_{LD} is our desired decoder.

Proof: Let c_1 be a transmitted word & y be the received word & $\Delta(c_1, y) \leq t$.

Assume: $D_{MLD}(y) = c_2 \neq c_1 \Rightarrow \Delta(c_2, y) \leq t$.

$$\Rightarrow \Delta(c_1, c_2) \leq \Delta(c_1, y) + \Delta(y, c_2)$$

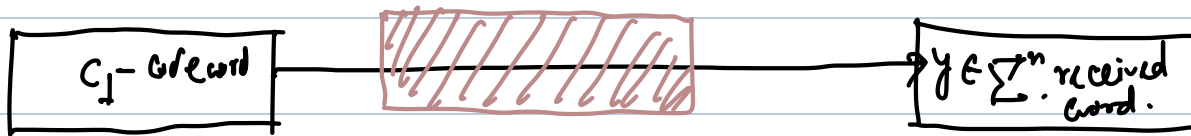
$$\leq t + t$$

$$< 2t \quad (\text{Contradiction})$$

$P1 \Rightarrow P3$

Error detection Algo: if $y \in C$, output 1.
otherwise 0.

(d-1)-error channel



if no error happens, then $y = c_1$,

if error happens, then $1 \leq \Delta(y, c_1) \leq d-1$.

$\Rightarrow y \notin C$.

$P1 \Rightarrow P4$: $y \in (\Sigma \cup ?)^n \rightarrow$ received code word.

$\exists$ unique code word $c = (c_1, \dots, c_n)$ s.t.

$y_i = c_i \quad \forall i \in [n] \text{ s.t. } y_i \neq ? \Rightarrow$ Exhaustive search.

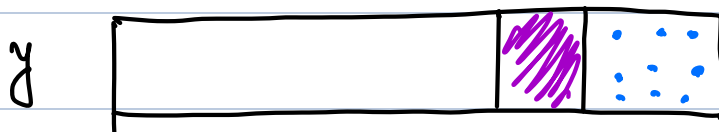
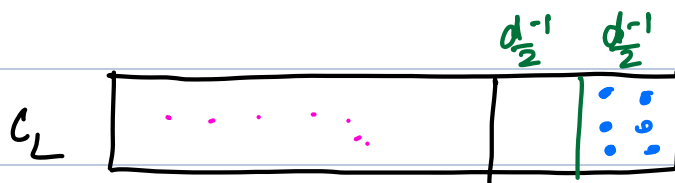
Contradiction: $\exists c_1 \neq c_2$ s.t. both agrees with y in unagreed

positions; $\Rightarrow \Delta(c_1, c_2) \leq d-1$

$TP_1 \Rightarrow TP_2, TP_3, TP_4$:

1. $TP_1 \Rightarrow TP_2$: $\Delta(c) < d = 2t+1$ & can correct $\frac{d-1}{2}$ errors (P_1) $\Rightarrow \perp$

$\Downarrow$
 $\exists c_1, c_2: \Delta(c_1, c_2) = d-1$



$\Delta(c_1, y) = \Delta(c_2, y) = \frac{d-1}{2}$

$\Rightarrow$ No decoding function can work.

Similar argument proves that $7P_1 \Rightarrow 7P_3, 7P_4$ (Exercise).

Error correction capability $\Leftrightarrow$ distance

Goal: minimizing redundancy & maximizing error-correction
 $\Downarrow$

maximizing rate & maximizing distance

Q: What is the largest rate R that a code with distance d can have?

Family of codes:

Until now, we have studied codes of fixed block lengths & dimensions. But, when we talk about algorithmic & lower bound questions related to code, it makes more sense to study a family of codes & their asymptotic rate & distance.

Code family, Rate & distance: Let $q \geq 2$. Let $\{n_i\}_{i \geq 1}$ be an increasing sequence of block lengths. Let $\{k_i\}_{i \geq 1}$ & $\{d_i\}_{i \geq 1}$ s.t. $\forall i \geq 1 \exists$ an $(n_i, k_i, d_i)_q$ code C_i . Then

$\mathcal{C} = \{C_i\}_{i \geq 1}$ is family of codes.

$R(\mathcal{C}) = \lim_{i \rightarrow \infty} \frac{k_i}{n_i}$, when limit exists.

Relative distance of $\mathcal{C}$, $\delta(\mathcal{C}) = \lim_{i \rightarrow \infty} \frac{d_i}{n_i}$, when limit exists.

Eg: $C_{3,rep}^{(i)}: \{0,1\}^i \rightarrow \{0,1\}^{3i}$ & $C = \{C_{3,rep}^{(i)}\}_{i \geq 1}$.

$(a_1, \dots, a_i) \rightarrow (a_1, a_1, a_1, a_2, a_2, a_2, \dots, a_i, a_i, a_i)$.

$$R(C) = \lim_{i \rightarrow \infty} \frac{i}{3i} = \frac{1}{3}$$

$$\delta(C) = \lim_{i \rightarrow \infty} \frac{3}{3i} = \lim_{i \rightarrow \infty} \frac{1}{i} = 0.$$

$\Rightarrow$ formally talk asymptotic running time of algorithms.

$\Rightarrow O(n^v)$ -time decoding algorithm for a code $C \Rightarrow$
implicitly $\exists$ a family of code C & that algorithm has running time
 $O(n^v)$ for large enough block.

Efficient algorithm $\Rightarrow \text{poly}(n)$.

Sabtle point: $\{C_i\}_{i \geq 1}$, each C_i is the same code but
with different parameters! [example: $\{C_{3,rep}^{(i)}\}_{i \geq 1}$.

Q: Given q , what is the optimal tradeoff b/w
 $R(C)$ & $\delta(C)$ that can be achieved by some family
of q -ary codes.

Q: Does $\exists$ a constant q & a q -ary family of codes $\mathcal{C}$ which is asymptotically good; i.e., both $R(\mathcal{C})$ & $\delta(\mathcal{C})$ are positive?

[observe that $\{\mathcal{C}_{\text{rep}}^{(i)}\}$ is not asymptotically good].